

# **TSC695 Evaluation Kit**

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## **Getting Started Guide**











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# Section 1

## Getting Started

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### 1.1 TSC695 Evaluation Kit Contents

The *TSC695* starter kit contains the following parts:

- Evaluation board equipped with:
  - TSC695 processor
  - 512Kbytes FLASH containing the *rdbmon* monitor program
  - 4Mbytes RAM
- Cables and adapters
  - RS232C standard serial straight thru cables DB9/DB9
  - Null-modem adapters DB9/DB9
  - RS232C serial adapters DB9/DB25
  - DC power cable
- TSC695 Starter-kit's CD-ROM
- Documentation
  - This Getting Started Guide

### 1.2 CD-ROM Contents

Launch “welcome.htm” file to have a graphic overview of CD-ROM contents.

The CDROM is organized as follows:

*/bsd* : contains the *TSC695 BSD* file

*/code\_example* : contains the code source of a short application displaying an “hello word” string

*/doc* : contains datasheets, specifications and user's guides in pdf format

*/erc32ccs* : contains the software packages of ERC32 GNU Cross-Compiler System

*/graf* : contains images files

*/html* : contains html files

*/leccs* : contains the software packages of LEON/ERC32 GNU Cross-Compiler System

*/patches* : contains files to patch the *CCS* packages

*/vhdl* : contains the *TSC695 VHDL* model and related files

CD-ROM updates may be downloaded from : <https://www.atmel-nantes.fr/aedos/>

It's necessary to get a User login and Password to access this web site.

They can be requested through our hotlines, by sending an email providing the following requester's data :

- First name
- Last name
- Company name
- Email address
- Starter-kit name or reference

The hotlines addresses are available from URL : <http://www.atmel.com/products/radhard/>

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### 1.3 Minimum Hardware Configuration

The following hardware must be provided by the user to have a complete working configuration :

- A SUN or PC machine with 2 available serial ports.
- USB / RS232C dongles can be used on PC platforms to get additional COM ports.
- A 5V DC power supply capable of supplying at least a current of 1A

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### 1.4 Getting Started with the Evaluation Kit

To get the software running on the *TSC695* evaluation board, you will need to follow the steps below (detailed in the next paragraphs) :

1. Connect the evaluation board serial connectors A and B to the *host* machine serial ports.
2. Connect the evaluation board to the DC power supply.
3. Install the software development package from the CDROM on your machine.
4. Compile and link your program.
5. Transfer your program executable file to the evaluation board RAM.
6. Debug/Run your program on board with *GDB* and its graphical user interface *DDD*.

## Section 2

# Hardware Installation

### 2.1 Connecting the Serial Links

The evaluation board provides two serial ports.

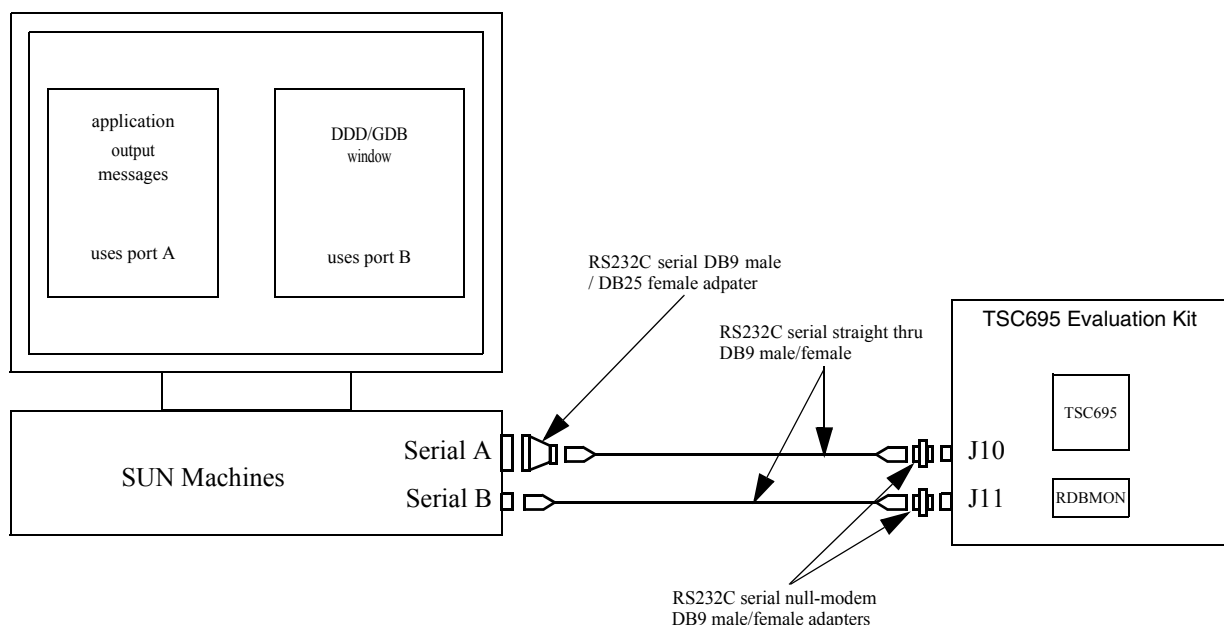
Serial A port is used by the application running on the evaluation board to establish a full-duplex connection and output data to the host.

Serial B port enables RDBMON, the on-board monitor program, to communicate with GDB application running on the host.

The host needs to have two available serial ports. It can be SUN or PC machines, but the shape and pinout are rather different between those platforms. This is why adapters are provided in this kit in addition to the RS232C standard cables.

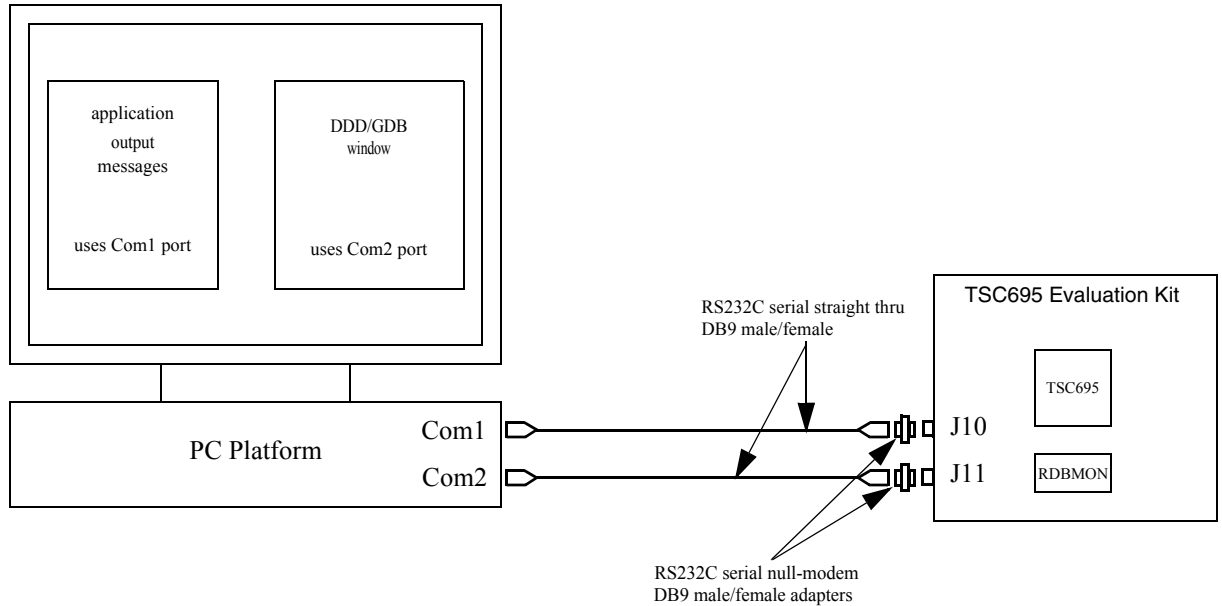
#### 2.1.1 SUN Machines

Connect the serial ports of the evaluation board to the ports of the host by means of RS232C serial straight thru DB9 male/female cables, serial DB9 male/DB25 male adapter, and serial null-modem DB9 male/female adapters.



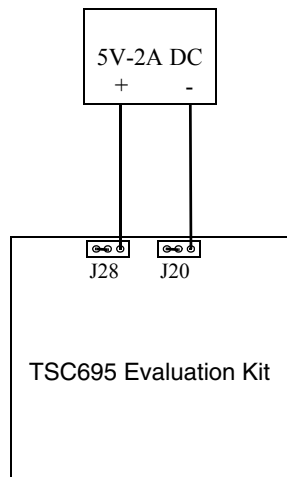
2.1.2 PC Machines

Connect the serial ports of the evaluation board to the ports of the host by means of RS232C serial straight thru DB9 male/female cables and serial null-modem DB9 male/female adapters



2.2 Connecting the Power Supply

Connect the board to a 5V-2A DC power supply as follows:  
**J28-C to VCC, J20-C to GND.**



## Section 3

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# ERC32CCS Software Package

- 
- 3.1 Supported Platforms**
- The Software Package is available from \erc32ccs folder of the starter-kit CD-ROM
- ERC32CCS is a set of tools supporting two host platforms :
- SPARC Solaris 2.5.1(or higher)
  - x86 linux (libc5).
- Further information is provided in erc32ccs-2.0.7.pdf document supplied in \erc32\doc\ directory of erc32ccs-2.0.7-linux.tar.gz package
- 
- 3.2 Installing the Software Development Package for Solaris**
- The *ERC32CCS* directory tree is compiled to reside in */opt/gnu* on *Solaris* platforms. If the installation directory is not */opt/gnu*, then you will have to create a link to the location of the *ERC32CCS* directory after installation.
1. Copy the *erc32ccs-2.0.6-solaris.tar.gz* file from the CDROM to your disk.
  2. Uncompress and extract the tar file.
  3. On your platform, create the link:
 

```
Solaris1>cd /opt/gnu
Solaris1>ln -s <install_dir>/erc32ccs-2.0.6-solaris/erc32
```
  4. Add */opt/gnu/erc32/bin* to your search path.
- 
- 3.3 Compiling and Linking your Program**
- Compile and link your application program as follows:
- ```
Solaris1>sparc-rtems-gcc -g -O3 application.c -o application
```
- 
- 3.4 Opening the Application Terminal Window**
- You must open a terminal window on the *Solaris* platform so that your application can display results. You do this with the command:
- ```
Solaris1>xterm -e tip -19200 /dev/ttya &
```
- 
- 3.5 Transferring the Executable File to the Board RAM**
- You may load and debug your application through *GDB* only, but working with *GDB* through *DDD* is much more easier.
- To start *DDD* with the debugger, use:
- ```
Solaris1>ddd --debugger sparc-rtems-gdb --no-data-window --attach-source-window <your_application>
```

A script, *dddx* is provided to start *DDD* in this configuration. Use *dddx* as follows:

**Solaris1>dddx <your\_application>**

You may also type *dddx* only and then specify the application to be loaded with the *DDD File > Open Program...* command.

### 3.6 Remotely Debugging your Program

You should now have two windows opened to debug your application: a terminal window and a *DDD* one.

Reset the board with the *S1 RESET* switch. The terminal window should display:

```
ERC32 boot loader v1.1
watchdog clock : 3.7 Mhz
Baudrate : 19200 baud
Prom : 512K, 4 ws
ram : 4069 K, 2 banks, 00 ws (r/w)
edac : enabled
parity : enabled
write-protect : 0x023f9000 - 0x023fad0
```

```
initialising ram memory
loading .text
loading .data
```

```
starting mon
rdbmon v1.1
```

In the *DDD* command window, perform the following steps:

```
(gdb) set remotebaud 19200
(gdb) target erc32 /dev/ttyb
Remote debugging using /dev/ttyb
0x2000000 in ?? ()
(gdb) load
Loading section .text, size 0x69a0 vma 0x2000000
Loading section .data, size 0x530 vma 0x20069a0
(gdb) run
```

You are now ready for a remote debugging session. The following figure shows a session example:

The screenshot shows the Atmel Studio IDE with the following components:

- Terminal Window (Left):**

```

tip
ERC32 boot loader v1.0
initialising RAM
loading .text
loading .data
starting mon

ERC32 boot loader v1.0
initialising RAM
loading .text
loading .data
starting mon

***** TSC695E DDD/GDB/RDBMON demo *****
Set GPI bus in output mode.
Clear GPI bus.
Set GPI(0) and clear GPI(7).
        
```
- Debugger Window (Right):**
  - File:** DDD: /mdplab/applab/products/sparc\_rt/tsc695e/demo\_ams/gpi\_blink.c
  - Registers:**
    - 10: \*GPIDATR: 0
    - 11: \*GPICNFR: 255
  - Source Code:**

```

do
{
    printf("%s\n", "Set GPI(0) and clear GPI(7).");
    *GPIDATR = *GPIDATR | 0x00000001;
    *GPIDATR = *GPIDATR & ~0x00000080;

    for(i = 7000000; i > 0; i--);

    printf("%s\n", "clear GPI(0) and set GPI(7).");
    *GPIDATR = *GPIDATR & ~0x00000001;
    *GPIDATR = *GPIDATR | 0x00000080;

    for(i = 7000000; i > 0; i--);

} while (!kbhit_X(0));
        
```
  - Assembly Code:**

```

Dump of assembler code from 0x2001630 to 0x2001730:
0x2001630 <main+144>:    or  %i0, 0x3c0, %o4
0x2001634 <main+148>:    ld  [ %o3 ], %o0
0x2001638 <main+152>:    or  %o0, 1, %o0
0x200163c <main+156>:    st  %o0, [ %o3 ]
        
```
  - Debugger Console:**

```

(gdb) graph undisplay 3
(gdb) graph undisplay 1
(gdb) graph display *GPIDATR
(gdb) graph display *GPICNFR
(gdb) !
        
```
  - Status Bar:** Display 10: \*GPIDATR (enabled, scope main)



## Section 4

# LECCS Software Packages

### 4.1 Supported Platforms

The Software Packages are available from \leccs folder of the starter-kit CD-ROM

LECCS is a multi-platform development system based on the GNU family of freely available tools. It is provided for three host platforms :

| Platform    | OS Version                         |
|-------------|------------------------------------|
| Linux / x86 | Linux-2.2.x, glibc-2.2 (or higher) |
| Solaris     | solaris-2.7 (or higher), gunzip    |
| MS Windows  | Cygwin-1.1.7 (or higher)           |

Further information is provided in leccs-1.1.1.pdf document supplied in \rtems\doc\tools\ directory of leccs-docs-tools-1.1.tar.gz package

### 4.2 Installing the Software Development Packages for MS Windows

To run on Windows platforms, Cywin unix emulation layer needs to be installed.

Cygwin is not provided in this starter-kit. It can be freely installed from [www.cygwin.com](http://www.cygwin.com) web site.

The LECCS directory tree is compiled to reside in `/opt/rtems` directory . If the installation directory is not `/opt/rtems`, then you will have to create a link to the location of the *LECCS* directory.

1. Copy the `leccs-cygwin-1.1.5.3.tar.gz` file from the CDROM to your disk.
2. Uncompress and extract the tar file.
3. On your platform, create the link:  

```
$ cd /opt
$ ln -s <install_dir>/leccs-cygwin-1.1.5.3/rtems
```
4. Add `/opt/rtems/bin` to your search path.

**Warning :** As Linux does not support paths containing blank characters, avoid to use the Home path inherited from Windows to locate your own development folders, if this one contains blank characters.

### 4.3 Compiling and Linking your Program

Compile and link your application program as follows:

```
$ sparc-rtems-gcc -g -O3 application.c -o application
```

- 
- 4.4 Opening the Application Terminal Window** You must open an Hyperterminal Window so that your application can display results. After launching Hyperterminal, select the appropriate COM port number and use the following port settings :
- Bits per second : 19200
  - Data bits : 8
  - Parity : None
  - Stop bits : 1
  - Flow control : None
- 
- 4.5 Transferring the Executable File to the Board RAM** You may load and debug your application through *GDB* only, but working with *GDB* through *DDD* is much more easier. To start *DDD* with the debugger, use:
- ```
$ ddd --debugger sparc-rtems-gdb --attach-window <your_application>
```
- You may also type only :
- ```
$ ddd --debugger sparc-rtems-gdb --attach-window
```
- and then specify the application to be loaded with the *DDD File > Open Program...* command.
- 
- 4.6 Remotely Debugging your Program** You should now have two windows opened to debug your application: a terminal window and a *DDD* one. Reset the board with the *S1 RESET* switch. The terminal window should display:
- ```
ERC32 boot loader v1.1
watchdog clock : 3.7 Mhz
Baudrate : 19200 baud
Prom : 512K, 4 ws
ram : 4069 K, 2 banks, 00 ws (r/w)
edac : enabled
parity : enabled
write-protect : 0x023f9000 - 0x023fad0
```
- ```
initialising ram memory
loading .text
loading .data
```
- ```
starting mon
rdbmon v1.1
```

In the DDD command window, perform the following steps:

(gdb) **set remotebaud 19200**

(gdb) **target erc32 /dev/ttyb**

Remote debugging using /dev/ttyb

0x2000000 in ?? ()

(gdb) **load**

Loading section .text, size 0x69a0 vma 0x2000000

Loading section .data, size 0x530 vma 0x20069a0

(gdb) **cont**

You are now ready for a remote debugging session.

The following figure shows a session example :

```

TSC695 - HyperTerminal
File Edit View Call Transfer Help
ERC32 boot loader v1.1
watchdog clock : 3.7 MHz
baud rate : 19200 baud
prom : 512 K
, 4 ws
ram : 4096 K, 2 banks, 0/0 ws (r/w)
edac : enabled
parity : enabled
write-protect : 0x023f9000 - 0x023fadc0
watchdog : enabled
initialising ram memory
loading .text
loading .data
starting mon
rdbmon v1.1 - bug reports to Jiri Gaisler, ESA (jgais@ws.estec.esa.nl)
Hello World...
Connected 0:15:20 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capture Print echo

```

```

DDD: /cygdrive/d/work-dev/world/world.c
File Edit View Program Commands Status Source Data Help
() : main
#include <stdio.h>

main() {
    puts ("Hello World...\n");
}

Dump of assembler code from 0x2001300 to 0x2001400:
0x2001300 <main+20>:   ret
0x2001304 <main+24>:   restore
0x2001308 <_puts_r>:   save %sp, -136, %sp
0x200130c <_puts_r+4>: call 0x200138c <strlen>
0x2001310 <_puts_r+8>: mov %il, %o0
0x2001314 <_puts_r+12>: mov %o0, %g2
0x2001318 <_puts_r+16>: ld [ %i0 + 8 ], %o0
0x200131c <_puts_r+20>: sethi %hi(0x2003800), %o1
0x2001320 <_puts_r+24>: or %o1, 0x2d0, %o1      ! 0x2003ad0 <_rodata_start+16>
0x2001324 <_puts_r+28>: add %g2, 1, %o5
0x2001328 <_puts_r+32>: add %fp, -40, %o4
0x200132c <_puts_r+36>: mov 1, %o2
0x2001330 <_puts_r+40>: mov 2, %o3
0x2001334 <_puts_r+44>: st %o1, [ %fp + -32 ]
0x2001338 <_puts_r+48>: st %il, [ %fp + -40 ]
0x200133c <_puts_r+52>: st %o2, [ %fp + -28 ]
0x2001340 <_puts_r+56>: st %o5, [ %fp + -16 ]
0x2001344 <_puts_r+60>: st %o4, [ %fp + -24 ]
0x2001348 <_puts_r+64>: st %o3, [ %fp + -20 ]
0x200134c <_puts_r+68>: st %g2, [ %fp + -36 ]
0x2001350 <_puts_r+72>: call 0x2001400 <__sfwwrite>
0x2001354 <_puts_r+76>: add %fp, -24, %o1
0x2001358 <_puts_r+80>: cmp %o0, 0
0x200135c <_puts_r+84>: be 0x2001368 <_puts_r+96>
0x2001360 <_puts_r+88>: mov 0xa, %i0
0x2001364 <_puts_r+92>: mov -1, %i0
0x2001368 <_puts_r+96>: ret
0x200136c <_puts_r+100>: restore
0x2001370 <puts>:      save %sp, -104, %sp
0x2001374 <puts+4>:      sethi %hi(0x2003c00), %o1
0x2001378 <puts+8>:      ld [ %o1 + 0x21c ], %o0      ! 0x2003e1c <_impure_ptr>
0x200137c <puts+12>:     call 0x2001308 <_puts_r>
0x2001380 <puts+16>:     mov %i0, %o1
0x2001384 <puts+20>:     ret
0x2001388 <puts+24>:     restore %g0, %o0, %o0

GNU DDD 3.3.9 (i686-pc-cygwin), by Dorothea Lütkehaus and Andreas Zeller.
Copyright © 1995-1999 Technische Universität Braunschweig, Germany.
Copyright © 1999-2001 Universität Passau, Germany.
Copyright © 2001 Universität des Saarlandes, Germany.
Copyright © 2001-2004 Free Software Foundation, Inc.
(gdb) set remotebaud 19200
(gdb) target extended-remote /dev/ttyS0
0x02000000 in text_start ()
(gdb) load
Loading section .text, size 0x3b20 lma 0x20000000
Loading section .data, size 0x750 lma 0x2003b20
Start address 0x20000000, load size 17008
Transfer rate: 7161 bits/sec, 274 bytes/write.
(gdb) cont

Program exited with code 0220.
(gdb)

```

△ Program exited with code 0220.

## Section 5

---

# Using the TSC695 VHDL Model

The starter kit contains a precompiled *VHDL* model of the *TSC695* device. The model has been compiled for use with the ModelSim V5.2e *VHDL* simulator. The model is already back-annotated by a *SDF* file in typical conditions (5V, 25C).

Before using the model, you must copy the *VITAL* libraries and the modelsim.ini file from the *CDROM*; then, modify the modelsim.ini file so that it fits with the libraries installation directory path.

For the *VHDL* model to operate properly, you must force some internal nets for a few cycles. A bus called D\_INIT (33 bits wide) is declared in the model entity. This bus is for the *TSC695 VHDL* model initialization purpose only. There is no D\_INIT bus on the device.

When writing your *VHDL* test bench or the *VHDL* description of the *TSC695* hardware environment, you must declare a S\_D\_INIT 33-bit wide std\_logic\_vector signal that you will connect to the D\_INIT one in the instantiation part of your *VHDL* design. You then add the following three lines to your startup.do file, or you keep them in a standalone file that you load on demand (but always at the very beginning of the simulation session).

```
force -freeze /<test_bench_entity>/S_D_INIT 16#0
```

```
run <10 cycles periods>
```

```
force -freeze /<test_bench_entity>/S_D_INIT 16#Z
```

If the system clock period is 100ns, the run statement is: run 1000ns.

S\_D\_INIT is a suggestion for the signal name. You may use any other signal name.



## Section 6

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# Where to go from here

The */opt/.../doc* folders contains getting started guides and the *DDD*, *GDB* and *GCC* manuals in *pdf* format.

You should also read the *TSC695* User's Manual and Data Sheet as well as the evaluation board User's Manual which describes the numerous capabilities of the evaluation hardware.

*Where to go from here*





## Atmel Corporation

2325 Orchard Parkway  
San Jose, CA 95131, USA  
Tel: 1(408) 441-0311  
Fax: 1(408) 487-2600

## Regional Headquarters

### Europe

Atmel Sarl  
Route des Arsenaux 41  
Case Postale 80  
CH-1705 Fribourg  
Switzerland  
Tel: (41) 26-426-5555  
Fax: (41) 26-426-5500

### Asia

Room 1219  
Chinachem Golden Plaza  
77 Mody Road Tsimshatsui  
East Kowloon  
Hong Kong  
Tel: (852) 2721-9778  
Fax: (852) 2722-1369

### Japan

9F, Tonetsu Shinkawa Bldg.  
1-24-8 Shinkawa  
Chuo-ku, Tokyo 104-0033  
Japan  
Tel: (81) 3-3523-3551  
Fax: (81) 3-3523-7581

## Atmel Operations

### Memory

2325 Orchard Parkway  
San Jose, CA 95131, USA  
Tel: 1(408) 441-0311  
Fax: 1(408) 436-4314

### Microcontrollers

2325 Orchard Parkway  
San Jose, CA 95131, USA  
Tel: 1(408) 441-0311  
Fax: 1(408) 436-4314

### La Chantrerie

BP 70602  
44306 Nantes Cedex 3, France  
Tel: (33) 2-40-18-18-18  
Fax: (33) 2-40-18-19-60

### ASIC/ASSP/Smart Cards

Zone Industrielle  
13106 Rousset Cedex, France  
Tel: (33) 4-42-53-60-00  
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Colorado Springs, CO 80906, USA  
Tel: 1(719) 576-3300  
Fax: 1(719) 540-1759

Scottish Enterprise Technology Park  
Maxwell Building  
East Kilbride G75 0QR, Scotland  
Tel: (44) 1355-803-000  
Fax: (44) 1355-242-743

### RF/Automotive

Theresienstrasse 2  
Postfach 3535  
74025 Heilbronn, Germany  
Tel: (49) 71-31-67-0  
Fax: (49) 71-31-67-2340

1150 East Cheyenne Mtn. Blvd.  
Colorado Springs, CO 80906, USA  
Tel: 1(719) 576-3300  
Fax: 1(719) 540-1759

### Biometrics/Imaging/Hi-Rel MPU/ High Speed Converters/RF Datacom

Avenue de Rochepleine  
BP 123  
38521 Saint-Egreve Cedex, France  
Tel: (33) 4-76-58-30-00  
Fax: (33) 4-76-58-34-80

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